

Polyphase Systems - Intro

☐ Introduction

- Objectives
- Vocabulary and background

☐ Analysis

- Comparison with single-phase
- Comparison with two-phase
- Currents and voltage in a three-phase system
- The Y-Connected generator (vocabulary and circuit intro)

Polyphase Systems- Objectives

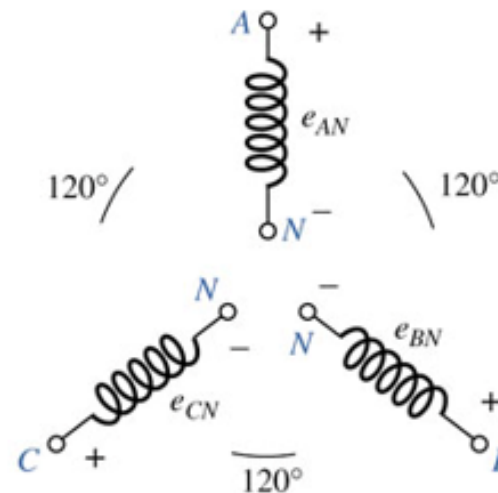
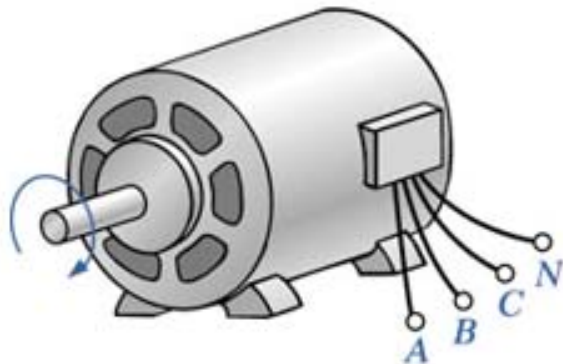
- Become familiar with the operation of a three-phase generator and the magnitude and phase relationship connecting the three phase voltages.
- Be able to calculate the voltages and currents for a three-phase Y-connected generator and Y-connected load.
- Understand the significance of the phase sequence for the generated voltages of a three-phase Y-connected or Δ -connected generator.
- Be able to calculate the voltages and currents for a three-phase-connected generator and Δ -connected load.

Polyphase Systems - Introduction

- An ac generator designed to develop a single sinusoidal voltage for each rotation of the shaft (rotor) is referred to as a single-phase ac generator.
- If the number of coils on the rotor is increased in a specified manner, the result is a polyphase ac generator, which develops more than one ac phase voltage per rotation of the rotor.
- In general, three-phase systems are preferred over single-phase systems for the transmission of power for many reasons, including the following:
 - 1. Thinner conductors can be used to transmit the same kVA at the same voltage, which reduces the amount of copper required (typically about 25% less) and in turn reduces construction and maintenance costs.
 - 2. The lighter lines are easier to install, and the supporting structures can be less massive and farther apart.
 - 3. Three-phase equipment and motors have preferred running and starting characteristics compared to single-phase systems because of a more even flow of power to the transducer than can be delivered with a single-phase supply.

Polyphase Systems - Introduction

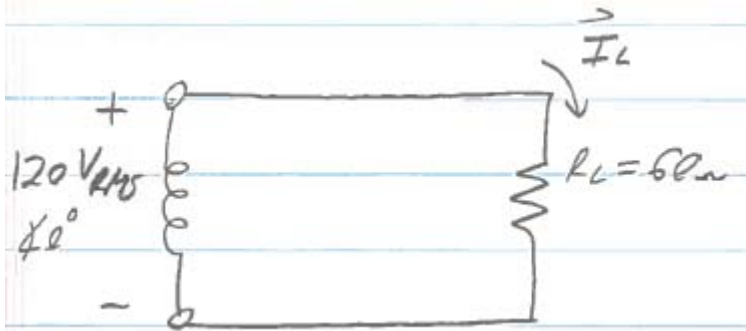
- In general, three-phase systems are preferred over single-phase systems for the transmission of power for many reasons, including the following:
 - 4. In general, most larger motors are three phase because they are essentially self-starting and do not require a special design or additional starting circuitry.



Same voltage magnitude on each coil, 120 degree phase-shift between waveforms

Polyphase Systems – Comparison with Single Phase

Consider the following single-phase system with a 240W load



$$P_{RL} = \frac{(120V_{RMS})^2}{60\Omega} = \boxed{240W}$$

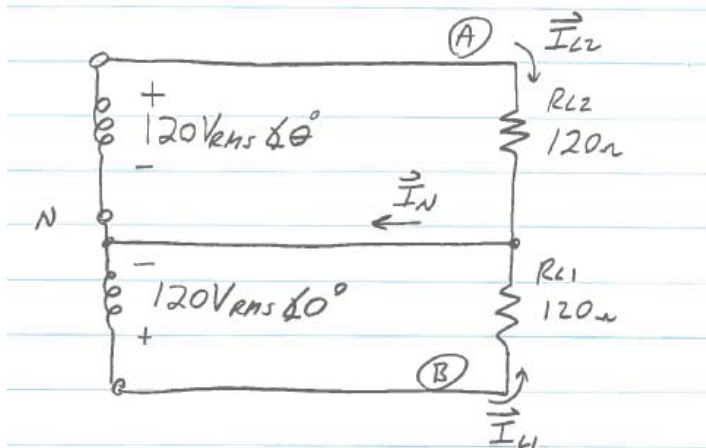
$$\vec{I}_L = \frac{120V_{RMS} \angle 0^\circ}{60\Omega} = \boxed{2A_{RMS} \angle 0^\circ}$$

Note: conductors are required to carry 2ARMS to AND from the load

Total copper cross section required: 2ARMS + 2ARMS = 4ARMS

Polyphase Systems – Comparison with Two-Phase

Consider the following two-phase system with a 240W load



$$\vec{I}_{L2} = \frac{120V_{rms} \angle \theta^\circ}{120\Omega} = 1A_{rms} \angle \theta^\circ$$

$$\vec{I}_{L1} = \frac{120V_{rms} \angle 0^\circ}{120\Omega} = 1A_{rms} \angle 0^\circ$$

$$P_T = [(1A_{rms})^2 120\Omega] \times 2 = \boxed{240W}$$

$$\vec{I}_N = 1A_{rms} \angle \theta^\circ + 1A_{rms} \angle 0^\circ$$

When will the neutral current, I_N be at a minimum? What is that value (of theta)?

$$\theta = 180^\circ: \vec{I}_N = 0A$$

Total copper cross section required: 1ARMS + 1ARMS = 2ARMS

- ½ of the single-phase case
- Assumes a balanced load ($I_N = 0A_{RMS}$)

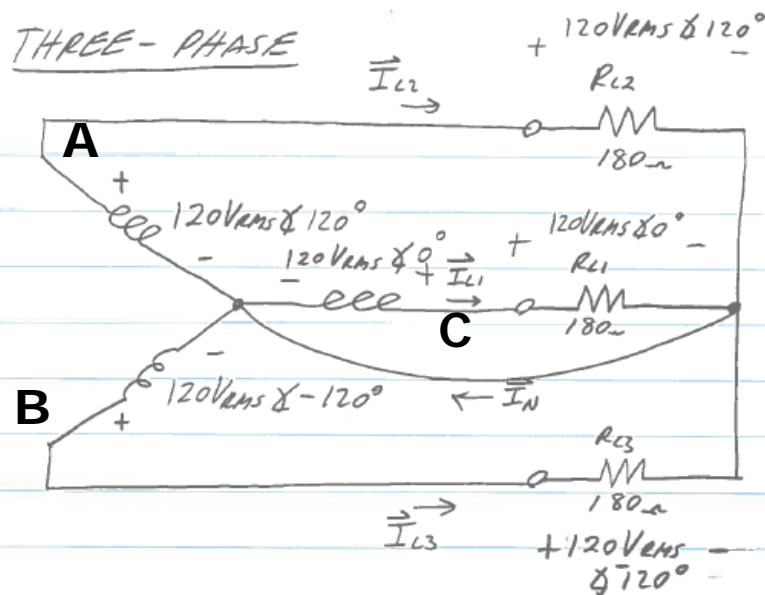
For $\theta = 180^\circ$, **find** $|V_{AB}|$ and $|I_{AN}|$ in RMS

For $\theta = 180^\circ$,

$|V_{AB}| = 240 V_{RMS}$ and
 $|I_{AN}| = 1A_{RMS}$

Three-Phase System – Currents and Voltages

Consider the following three-phase system with a 240W load



$$\vec{I}_{L1} = \frac{120V_{rms} \angle 0^\circ}{180\Omega} = 0.667A_{rms} \angle 0^\circ$$

$$\vec{I}_{L2} = \frac{120V_{rms} \angle 120^\circ}{180\Omega} = 0.667A_{rms} \angle 120^\circ$$

$$\vec{I}_{L3} = \frac{120V_{rms} \angle -120^\circ}{180\Omega} = 0.667A_{rms} \angle -120^\circ$$

$$P_{L1} = P_{L2} = P_{L3} = (0.667A_{rms})^2 180\Omega = 80W$$

$$P_T = 240W \leftarrow 240W \text{ LOAD}$$

Find: I_N and the total copper cross-section required to deliver 240W of power:

$$\vec{I}_N = \vec{I}_{L1} + \vec{I}_{L2} + \vec{I}_{L3}$$

For this balanced-load:

$I_N = 0A_{rms}$ and the total copper cross-section required is:

$$0.667A_{rms} + 0.667A_{rms} + 0.667A_{rms} = 2A_{rms}$$

Much better than the single-phase case and less than two-phase for unbalanced loads

What about $|V_{AB}|$?

This line-voltage is 207.9VRMS, less than the 240VRMS required for the two-phase case

Three-Phase System – Currents and Voltages

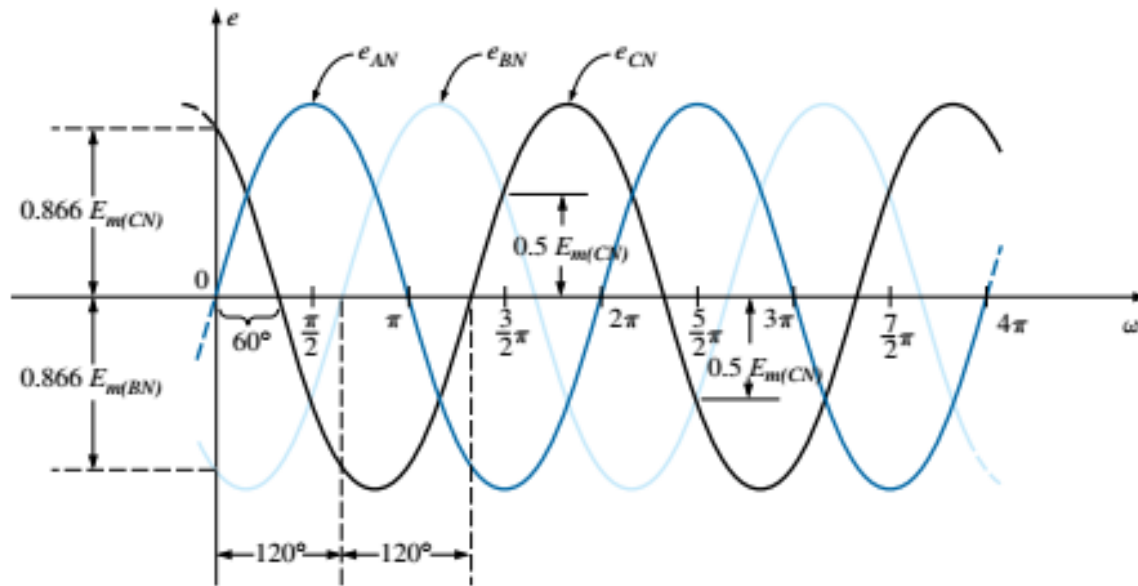


FIG. 24.2

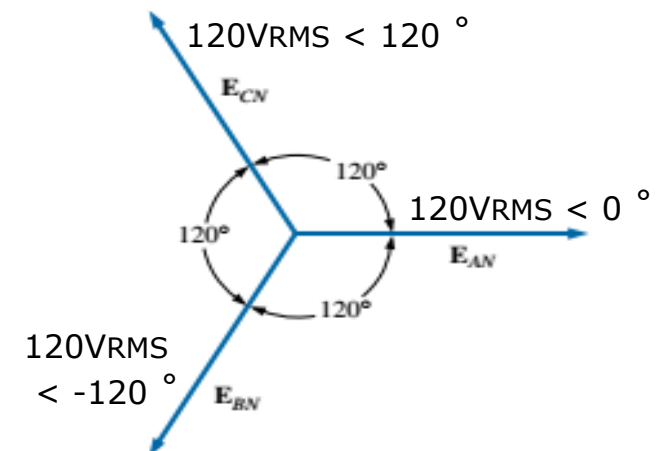
Phase voltages of a three-phase generator.

Phase voltages as functions of time:

- At any "t," the algebraic sum of the three phase voltages = 0V
- When one phase voltage = 0V, the other two are at 86.6% of their positive or negative maximums
- When any two phase voltages are equal in magnitude and sign (at $0.5E_m$), the remaining phase voltage has the opposite polarity and is at it's peak value

Phase voltages as vectors (phasor diagram):

- The phasor sum of the phase voltages = 0



$$\mathbf{E}_{AN} + \mathbf{E}_{BN} + \mathbf{E}_{CN} = 0$$

Phasor diagram for the phase voltages of a three-phase generator.

Polyphase Systems – The Y Connected Generator

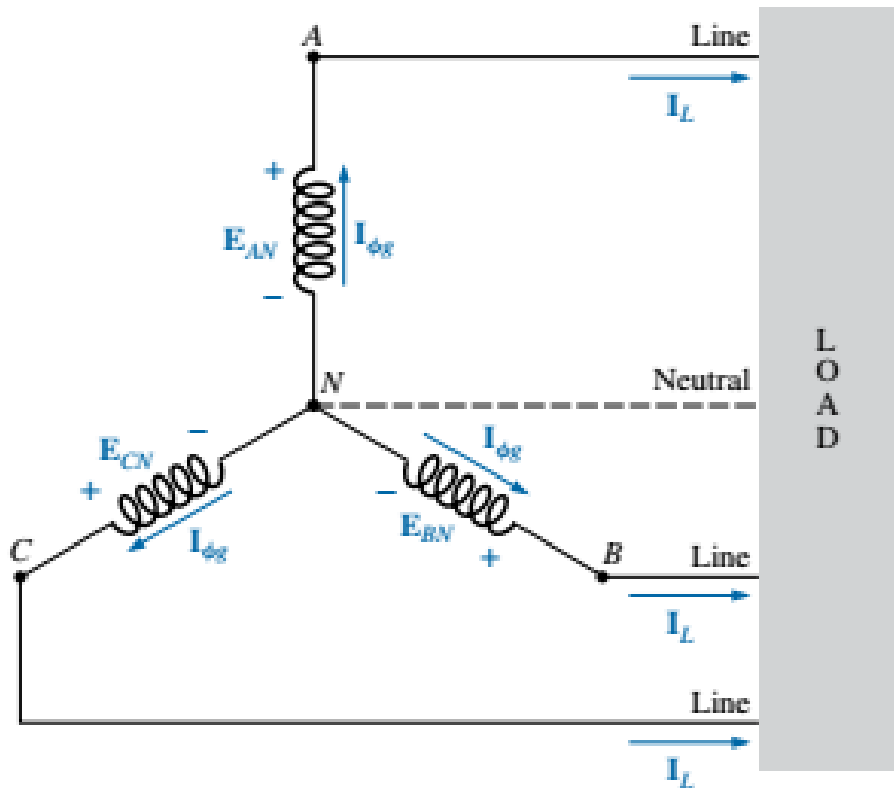


FIG. 24.5

Y-connected generator.

PHASE VOLTAGES

$$\vec{E}_{AN}, \vec{E}_{BN}, \vec{E}_{CN}$$

PHASE CURRENTS

I_{ϕ} : EQUAL FOR A BALANCED LOAD

LINE CURRENTS

$$I_L = I_{\phi}$$

LINE VOLTAGES

$$\vec{E}_{AB} = \vec{E}_{AN} - \vec{E}_{BN}$$

$$\vec{E}_{BC} = \vec{E}_{BN} - \vec{E}_{CN}$$

$$\vec{E}_{CA} = \vec{E}_{CN} - \vec{E}_{AN}$$

We will begin with an in-class problem on Wednesday using this system with a balanced load